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1 **Formation and Compaction of Sub-10 nm Transfer Films in Metal–** 2 **Ceramic Fretting**

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11 **Abstract**

12 Nanoscale transfer in metal–ceramic fretting originates at microcontacts but has remained experi-
13 mentally unresolved. Here, we use an atomic force microscopy (AFM)-based topographical differ-
14 ence method to visualize the formation of sub-10 nm transfer films at a sapphire–chromium inter-
15 face subjected to fretting. Transfer proceeds via adhesive wear of chromium at micrometer-scale
16 contacts, followed by plastic compaction of the chromium debris into a conformal ~5 nm transfer
17 film. Excess debris is expelled from the circular contact and accumulates in a curvature-defined pe-
18 ripheral ring around the contact. These results connect microcontact fracture, debris evolution, and
19 nanoscale transfer-film formation in fretting contacts.

20 **Keywords**

21 adhesive wear; atomic force microscopy; fretting; metal–ceramic interface; transfer film

22 1 Introduction

23 Precision interfaces subjected to cyclic tangential forces are designed to avoid gross sliding, yet
24 they can undergo progressive nanoscale material transfer [1-3]. Even a few nanometers of redis-
25 tributed material can alter the interfacial topography, leading not only to measurable height off-
26 sets [1] but also to changes in local roughness that affect friction and adhesion response. In semi-
27 conductor lithography, such transfer at metal–ceramic contacts [4-6] can degrade overlay and focus
28 stability. However, the physical processes by which microcontacts transition from deformation to
29 material transfer under partial slip [7] remain poorly understood.

30 The onset of material transfer under partial slip is governed by the local contact mechanics of
31 rough interfaces [8,9]. Classical Hertzian theory [10] describes the stress distribution in elas-
32 tic sphere-on-flat contacts, while the partial-slip solutions of Cattaneo [11,12], Mindlin [13], and
33 Johnson [14,15] show that tangential loading produces a central stick region surrounded by a slip-
34 ping annulus. In real, rough contacts, however, the interface is composed of discrete microcontacts,
35 each experiencing different normal and tangential stresses [16]. As a result, local stress ratios can
36 approach or exceed thresholds for slip or fracture even when the nominal interface remains below
37 the macroscopic sliding limit [17-22].

38 Classical contact theories assume smooth bodies [10,13], whereas real interfaces are rough and
39 composed of interacting asperities across multiple length scales [23]. Multiscale contact mechanics
40 frameworks, such as that of Persson [24-27], describe how load is distributed over a hierarchy of
41 microcontacts and how the real contact area evolves with applied pressure. Crucially, this stress
42 redistribution leads to highly heterogeneous local conditions, with some asperities experiencing
43 elevated pressures and shear stresses [25,27].

44 Building on multiscale contact mechanics, recent multi-asperity friction experiments have shown
45 that individual microcontacts within a nominal interface can simultaneously occupy subcritical,
46 partial-slip, and critically loaded states [28]. This heterogeneity implies that even when the macro-
47 scopic interface remains below the sliding threshold, certain asperities may experience stresses
48 sufficient to induce slip or material detachment. Early tribological studies by Miyoshi and co-

49 workers [5,6] demonstrated that adhesive interactions in metal–ceramic contacts can promote local
50 plastic shearing and material transfer once partial slip develops. However, these macroscopic ob-
51 servations did not resolve how debris nucleates and evolves at the nanoscale [29] within a realistic
52 multi-asperity contact.

53 Adhesive wear can be understood in terms of a critical length scale that separates plastic smoothing
54 from fracture-mediated debris formation. Aghababaei and Molinari showed that contact patches
55 smaller than a material-dependent threshold deform plastically [30], whereas larger junctions frac-
56 ture and generate wear particles [31]. Under reciprocated sliding, such debris can spread, com-
57 pact, and evolve into extended third bodies or transfer films [32,33]. However, how this transition
58 from microcontact growth to debris formation and film evolution manifests within realistic multi-
59 asperity contacts [34] operating under partial slip remains experimentally unresolved.

60 Experimentally, fretting-induced transfer has primarily been characterized at the microscale us-
61 ing optical microscopy, profilometry, SEM, EDX, and TEM. These techniques reveal wear scars,
62 debris accumulation, and mature tribofilms, but are typically applied after material redistribution
63 has reached micrometer dimensions [6,35-38]. As a result, the transition from asperity-scale defor-
64 mation to debris nucleation and nanoscale transfer-film formation remains unresolved. Although
65 atomic force microscopy (AFM) offers sub-nanometer sensitivity to topography, adhesion, and dis-
66 sipation [39-45], it has only rarely been applied to visualize the onset of transfer across a realistic
67 multi-asperity fretting interface [46].

68 In this work, we combine controlled partial-slip fretting with nanoscale-resolved AFM topogra-
69 phy difference mapping to resolve the onset of transfer-film formation at a multi-asperity sapphire–
70 chromium interface. We directly visualize the nucleation of a sub-10 nm conformal transfer film
71 and correlate it with micrometer-scale crater formation on the chromium surface. By integrating
72 contact mechanics simulations with critical length scale analysis, we examine when microcon-
73 tacts transition from plastic deformation to fracture-mediated debris generation. The results sup-
74 port a two-step mechanism in which micrometer-scale contact patches produce fractured chromium
75 fragments that are subsequently compacted into a conformal film, while excess debris is expelled

76 and accumulates at the contact periphery. This approach establishes a mechanistic link between
 77 asperity-scale fracture, debris evolution, and nanoscale transfer-film formation in fretting contacts.

78 2 Experimental

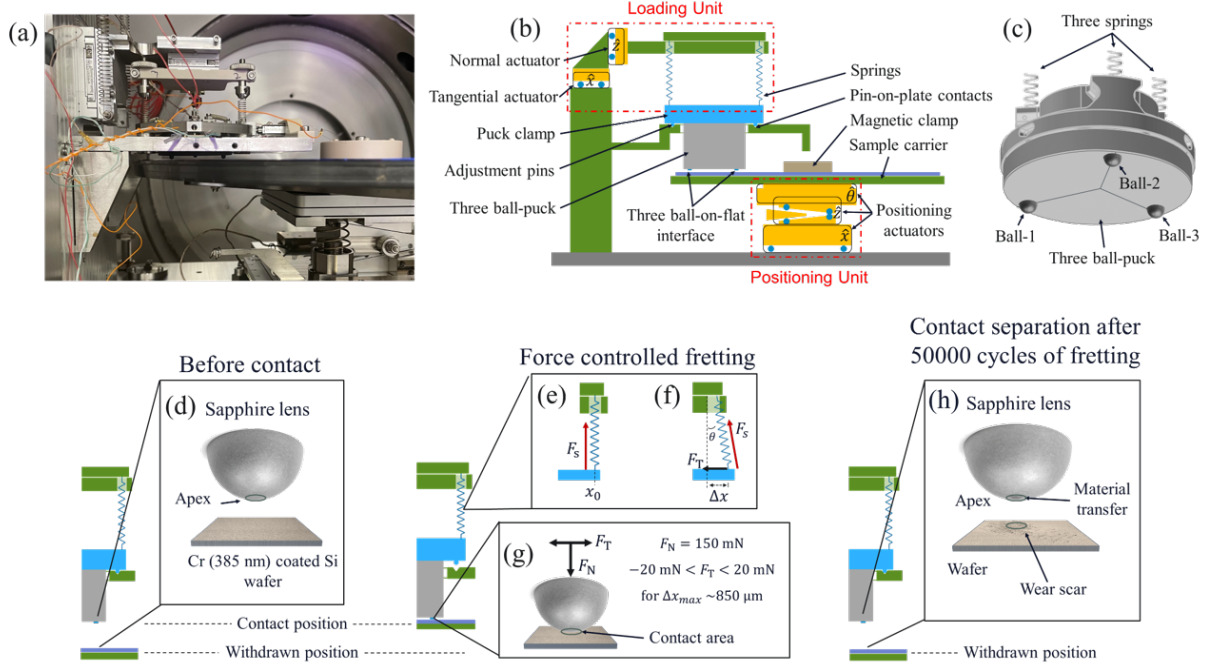


Figure 1: (a) Photograph of the customized tribometer installed inside a vacuum chamber. (b) Two-dimensional schematic of the tribometer reproduced from [21] (© 2023 J. Du et al., distributed under the terms of the Creative Commons Attribution 4.0 International License). The setup consists of a loading unit with normal and tangential actuators coupled to a three-ball puck through springs, and a positioning unit providing lateral (\hat{x}), normal (\hat{z}), and rotational ($\hat{\Theta}$) motion of the wafer. (c) Three-ball puck assembly (280 g). (d–h) Fretting protocol: (d) aligned sapphire lens ($R = 1.59 \text{ mm}$) and Cr-coated Si wafer (Cr thickness 750 nm) before contact; (e) application of the normal load F_N through spring loading; (f) oscillatory lateral displacement Δx_{max} generating tangential force F_T ; (g) imposed loading conditions ($F_N = 150 \text{ mN}$, $-20 < F_T < 20 \text{ mN}$, $\Delta x_{\text{max}} \sim \pm 850 \mu\text{m}$); (h) chromium transfer film on sapphire and corresponding wear scar on the Cr-coated wafer after 50 000 fretting cycles.

79 To ensure optimally aligned and force-controlled contact and fretting, we employed a customized
 80 three-ball-on-flat tribometer (Figure 1a) [21] located inside a clean room (ISO14644-Part 1, Class
 81 6). The instrument consists of (Figure 1b): (1) a loading unit containing normal and tangential ac-
 82 tuators coupled to the three-ball puck through three springs (TEVEMA T40730A, spring constant
 83 $k = 3.64 \text{ N mm}^{-1}$, free length $L_0 = 17.7 \text{ mm}$, maximum extension $S_n = 55.93 \text{ mm}$), and (2) a

84 positioning unit providing lateral (\hat{x}), normal (\hat{z}), and rotational ($\hat{\theta}$) motion for precise positioning
85 of the wafer substrate, which is fixed with a magnetic clamp onto the sample carrier beneath the
86 three-ball puck (Figure 1c).

87 The three springs mechanically couple the loading unit to the puck holder, enabling control over
88 the three-ball-on-wafer normal and tangential force. Application of an oscillating tangential force
89 can thus lead to fretting conditions when this tangential force remains below the friction thresh-
90 old of the system. During fretting, the interface undergoes only partial slip rather than gross slid-
91 ing [37].

92 As the ceramic counter bodies, we used three polished sapphire half-ball lenses (Edmund Op-
93 tics; diameter 3.18 mm). Sapphire was chosen because it is a hard, chemically inert ceramic rep-
94 resentative of the materials used in precision positioning interfaces. The metallic counterpart
95 was a chromium-coated silicon wafer comprising a 750 nm thick Cr film on a p-type Si substrate
96 (Siegert Wafer, $\langle 100 \rangle$, boron-doped, 500–525 μm thick, 1–10 $\Omega\cdot\text{cm}$) coated using magnetron sput-
97 tering physical vapor deposition. Chromium films are widely employed as adhesion, reference, and
98 clamping-contact layers in semiconductor tooling, making this sapphire–Cr pair a representative
99 model system for industrial metal–ceramic fretting interfaces.

100 Before loading, the puck assembly rested on three adjustment pins seated in pin-on-plate contacts
101 (Figure 1d), which were previously aligned with the sample on the positioning unit. Using the posi-
102 tioning unit, the wafer was positioned beneath the sapphire lenses. The puck assembly (Figure 1d)
103 weighs 280 g, resulting in a downward gravitational force of approximately 2.75 N. To reduce the
104 puck-on-wafer contact force, the three springs apply tension, such that the puck is resting on the
105 V-grooves with a total normal force of 450 mN (150 mN per contact). In other words, the springs
106 compensate part of the gravitational force on the puck. As the wafer was subsequently lifted toward
107 the puck, making contact with the sapphire lenses, the adjustment pins disengaged and 150 mN
108 normal force was applied to each sapphire-on-wafer contact (Figure 1e,g).

109 To ensure that the sapphire–wafer interface operated in the pre-sliding regime, we applied a sinu-
110 soidal tangential displacement at 1 Hz using the tangential actuator connected to the upper ends of

111 the springs. The actuator motion imposed a lateral displacement amplitude of $\Delta x_{\max} \sim \pm 850 \mu\text{m}$,
112 generating a corresponding tangential force of $-20 < F_T < 20 \text{ mN}$ on each sapphire ball-on-wafer
113 contact (Figure 1f,g). Together with the applied normal load of $F_N = 150 \text{ mN}$, this loading ratio
114 maintains the local tangential-to-normal stress ratio ($\mu = F_T/F_N \sim 0.13$) below the reported fric-
115 tion threshold values for sapphire–metal interfaces ($\mu \sim 0.5$) [47,48], thereby initiating controlled
116 partial slip without inducing gross sliding of the microcontacts within the three-ball-on-flat inter-
117 face.

118 We subjected the interface to 50 000 fretting cycles under these loading conditions to simulate a
119 small but representative fraction of motion cycles experienced by precision contacts in semicon-
120 ductor lithography tools, enabling accelerated study of early-stage material transfer phenomena.
121 After fretting, the positioning unit was retracted to separate the sapphire-on-wafer contacts. This
122 revealed a transfer film on the sapphire apex and a corresponding wear scar on the Cr-coated wafer
123 (Figure 1h).

124 Surface characterization before and after fretting was performed using a Bruker Dimension Icon
125 AFM operated in PeakForce QNM mode with a diamond probe (Adama Innovations AD-2.8-AS;
126 spring constant 2.8 N/m, resonance 65 kHz, apex radius $10 \pm 5 \text{ nm}$). Topography and adhesion
127 maps were simultaneously acquired to assess transfer-film development and changes in interfacial
128 properties. Detecting changes in topography at the nanometer scale is challenging. Therefore, we
129 complemented the topography measurements with local adhesion measurements, as adhesion is
130 a sensitive indication of local chemical and mechanical heterogeneity [43,45]. The smoothness
131 of both the sapphire and Cr-coated wafer surfaces ensures stable high-resolution operation, while
132 the robust diamond tip resists wear. The low spring constant offers enhanced force sensitivity and
133 tolerates topographic variation over larger scanned regions at the ball apex.

134 To quantitatively examine how roughness evolves across spatial scales, we computed the root-
135 mean-square (RMS) roughness as a function of scan window size using a sliding-window ap-
136 proach [49,50]. This analysis was applied to AFM topographs acquired from both the sapphire and
137 chromium surfaces.

138 To gain further insight into the interfacial contact behavior and enable predictive modeling, we
139 used Tamaas, which implements an FFT-accelerated boundary and volume integral method [51,52]
140 for solving rough elasto-plastic contact problems (see Supporting Information for details). By con-
141 ducting elasto-plastic contact computations of the sapphire–chromium interface, we resolved the
142 contact geometry, local pressure distribution, displacement fields, interfacial gap evolution, and
143 plastic strains under applied loads. AFM topographs of both the sapphire apex and the chromium-
144 coated wafer recorded prior to fretting served as input for these calculations, enabling a realistic
145 simulation of the elastic and plastic contact response at the interface.

146 **3 Results**

147 Figures 2a and 2b show the AFM scans acquired on the sapphire sphere and the chromium sur-
148 face, respectively. Figure 2c displays the scale-dependent RMS roughness, evaluated using sliding
149 square windows of increasing size [49,50], extracted from the AFM images shown in Figures 2a
150 and 2b. The chromium surface exhibits consistently low roughness values around 4 nm, indicating
151 high uniformity. In contrast, the RMS roughness of the sapphire lens increases with window size
152 and stabilizes beyond $8 \times 8 \mu\text{m}^2$. The error ranges indicated by shaded areas in Figure 2c represent
153 the spatial variability across the scanned region, demonstrating that roughness is highly location-
154 and scale-dependent, especially for inhomogeneous surfaces like the polished sapphire apex.

155 Microcontact size and local contact pressure are key parameters governing material transfer during
156 fretting. To obtain predictive insight, we combined classical Hertzian contact mechanics [10,15]
157 with Tamaas-based [51,52] elasto-plastic contact calculations. Figure 2d illustrates the classi-
158 cal Hertzian approach for a sapphire lens contacting a chromium-coated surface. With sapphire
159 and chromium Young’s moduli of 335 GPa [53] and 279 GPa [54,55], respectively, we computed
160 the reduced modulus $E^* \sim 161 \text{ GPa}$. At a contact force of 150 mN, and with a lens diame-
161 ter of 3.18 mm, Hertz theory yields a contact radius $a \sim 10 \mu\text{m}$, a maximum contact pressure
162 $p_{\text{max}} \sim 693 \text{ MPa}$, and an average contact pressure $p_{\text{avg}} \sim 462 \text{ MPa}$.

163 The AFM topographs shown in Figures 2a and 2b served as input for the elasto-plastic numeri-

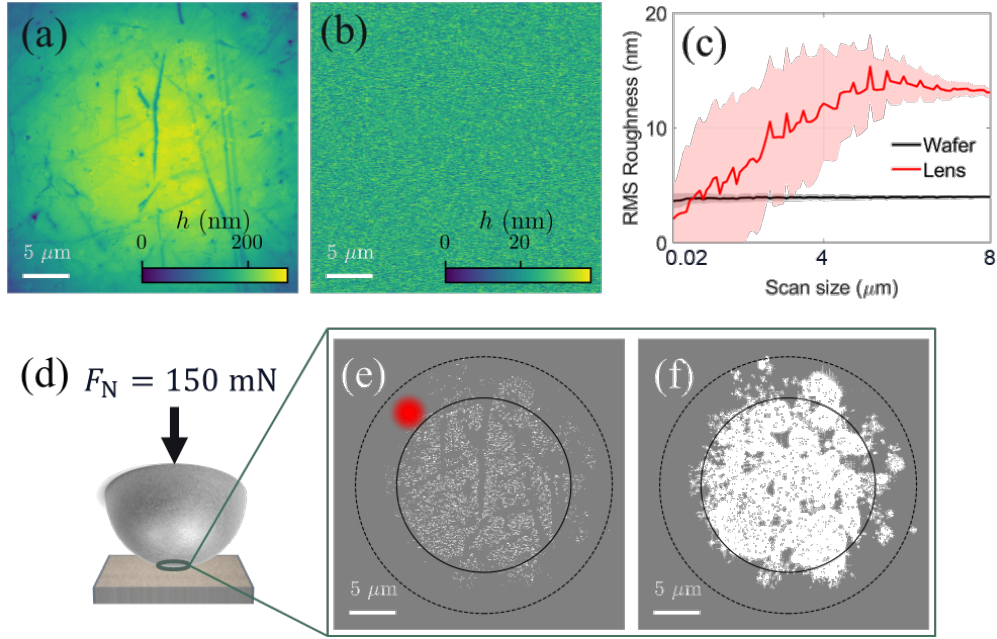


Figure 2: AFM topograph acquired from (a) the sapphire apex and (b) the chromium film. (c) Scale-dependent root-mean-square (RMS) roughness evaluated over sliding square windows [49,50] of increasing scan size for the counterparts before fretting. The lines denote the mean RMS value over all possible window positions for a given size, and the shaded areas represent the corresponding standard deviation. (d) Schematic of the sapphire-on-chromium contact under the applied normal load $F_N = 150$ mN. Contact simulations [51,52] based on the measured topographies yield (e) a binary contact map and (f) the local contact pressure distribution. The black circles indicate the estimated Hertzian contact area (with radius $a \sim 10$ μm). The red disk in (e) provides a visual reference for the estimated critical length scale d^* ; several micrometer-scale contact clusters are comparable in lateral size and are therefore candidates for fracture-mediated debris formation, as discussed below. The red marker on the color bar in (f) denotes 1 GPa, above which local plastic deformation of the chromium film is expected.

164 cal calculations achieved with Tamaas [51] (see Supporting Information for details). The contact
 165 map in Figure 2e reveals that the interface is composed of multiple discrete microcontacts, mostly
 166 within the calculated Hertzian contact. Several contact clusters reach micrometer-scale lateral di-
 167 mensions comparable to the red disk, which provides a visual reference for the estimated critical
 168 length scale for adhesive wear. These clusters are therefore candidates for fracture-mediated debris
 169 formation (see Discussion). In addition, Figure 2f shows that many contact regions experience lo-
 170 cal pressures exceeding 1 GPa, as indicated by the red marker on the color bar, suggesting that plas-
 171 tic deformation of the chromium film may occur during the experiment, and justifying the choice
 172 of an elasto-plastic contact computation rather than a purely elastic one. The real contact area in

Apex **before** and **after** fretting

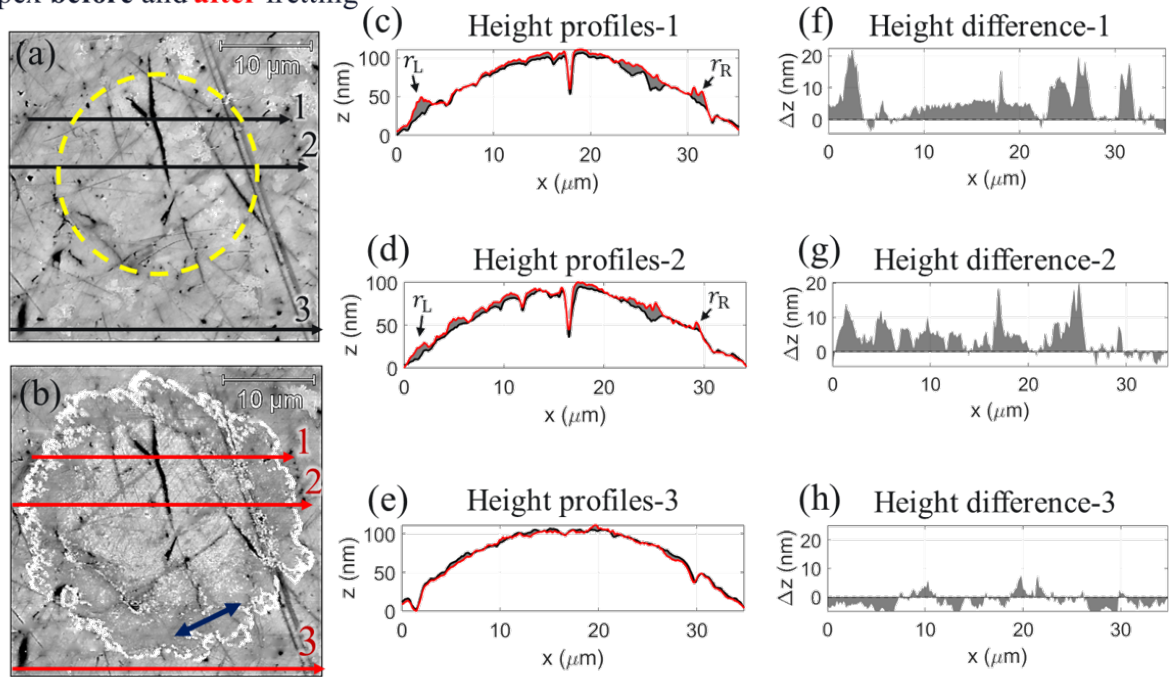


Figure 3: AFM height maps of the sapphire apex (a) before and (b) after fretting from a $34 \mu\text{m} \times 34 \mu\text{m}$ scan area (512×512 pixels). The yellow dashed circle indicates the Hertzian contact area, and the dark blue arrow indicates the fretting direction. A nanometric transfer film forms within the contact region in (b), within the predicted Hertzian contact radius ($\sim 10 \mu\text{m}$), while the peripheral ring reveals a thicker profile as indicated by r_L and r_R . (c,d) Trenches visible in both images are filled by transferred material. (c–e) Height profiles represent the black and red arrows from (a) and (b). (f–h) Height difference plots taken from the gray colored areas between the black and the red profiles in (c–e).

173 the elastic-plastic computation is roughly 30% larger than in a purely elastic computation. To quan-
 174 tify material transfer experimentally, we performed a comparative analysis of AFM topographs
 175 acquired before and after fretting.

176 Using a topographical difference approach, we extracted co-located cross-sectional height profiles
 177 to assess the material transfer and the spatial extent of surface modification. Figure 3a and 3b show
 178 AFM height maps of the sapphire apex measured before and after fretting. The sapphire surface
 179 initially exhibits shallow trenches and nanoscale polishing marks. After fretting, two distinct trans-
 180 fer regions appear: the first is a thin, conformal transfer film covering the predicted Hertzian con-
 181 tact area, and the second is a surrounding narrow outer ring consisting of relatively larger debris

182 particles. Trenches visible in both images are partially filled with transferred material from the
 183 chromium surface.

184 Height profiles extracted along the arrows in Figure 3(g,h) quantitatively compare the topographic
 185 evolution. Height and difference profiles reveal a median height increase of approximately 5 nm
 186 within the Hertzian contact area (Figure 3f and 3g). The height profiles measured after fretting
 187 exhibit two protrusions from the peripheral ring, denoted as r_L and r_R , with peak heights of 15–
 188 20 nm. The peripheral ring of transferred debris is approximately $4 \mu\text{m}$ outside the Hertzian con-
 189 tact. Furthermore, the two broader grooves on the sapphire surface become progressively filled
 190 by transferred debris, as indicated by the local height increase in the difference profiles (Fig-
 191 ure 3c,d,f,g). Outside the wear scar, only minimal difference between before and after topography
 192 measurement is observed ($\sim 0.2 \text{ nm}$), confirming the stability and repeatability of the topographic
 193 measurement.

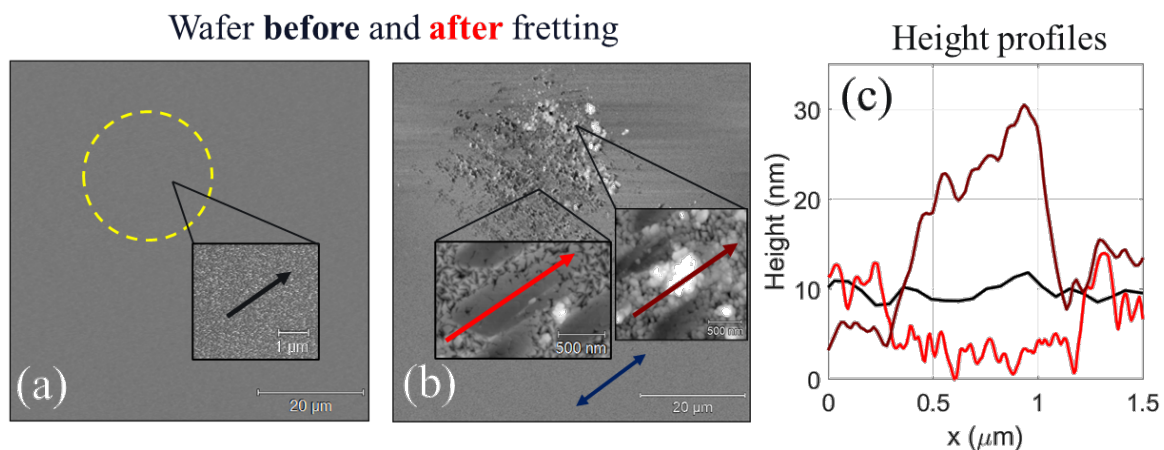


Figure 4: AFM topography images of the chromium-coated wafer (a) before and (b) after fretting, acquired over a $68 \mu\text{m} \times 68 \mu\text{m}$ area (1024×1024 pixels). The post-fretting image exhibits a well-defined wear scar that overlaps with the Hertzian contact area, indicated by the yellow dashed circle. The insets highlight (a) the pristine chromium surface covered by a native oxide and (b) local fretting-induced features, including craters in the center and debris accumulation at the periphery. The dark blue arrow denotes the fretting direction. (c) Height profiles reveal the surface modulation induced by fretting.

194 Figures 4a and 4b show AFM height maps of the chromium-coated wafer before and after fret-
 195 ting, providing direct evidence of fretting-induced surface restructuring and material displacement.
 196 Prior to fretting, the chromium surface exhibits a uniform granular texture with minimal height

197 variation. After fretting, a well-defined wear scar develops within and around the Hertzian contact
 198 region, with a lateral extent that closely matches the material transfer zone observed on the sap-
 199 phire surface (Figure 3b).
 200 The insets in Figure 4b highlight local craters formed near the center of the wear scar and debris
 201 accumulation at the periphery. The craters are elongated along the fretting direction and are sur-
 202 rounded by flake-like surface features, indicating a shear-driven detachment process. It is important
 203 to emphasize the aspect ratios of the craters and debris particles: both the craters and the debris
 204 particles are extended in the contact plane, in some cases beyond a micrometer, but very shallow
 205 (tens of nanometers in depth/height; see Figure 4).

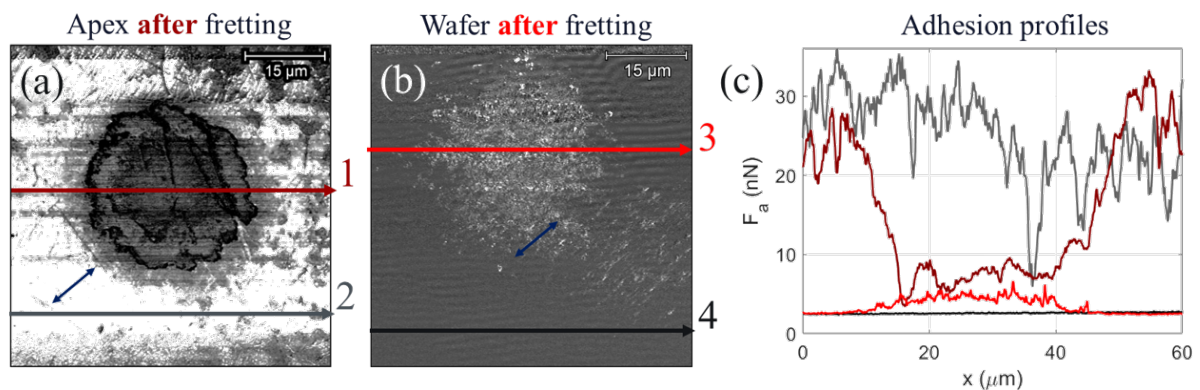


Figure 5: Adhesion maps of (a) the sapphire apex and (b) the wear scar on the chromium surface after fretting measured in PeakForce QNM mode using the same AFM tip (Adama Innovations, AD-2.8-AS). The dark blue arrow indicates the fretting direction. (c) Adhesion profiles extracted along the corresponding marked positions (in a and b). The dark red profile along the transferred material at the ball apex exhibits lower adhesion compared to the dark gray profile from surrounding pristine sapphire regions. The red profile along the wear scar on the chromium-coated wafer shows higher adhesion compared to the black profile from surrounding flat chromium film. The contrast between reduced adhesion on the sapphire and enhanced adhesion on the chromium confirms asymmetric interfacial evolution during material transfer, correlating with the topographic profiles shown in Figures 3 and 4.

206 The adhesion measurements highlight local contrast in adhesion likely caused by material transfer.
 207 On the sapphire apex (Figure 5a), the region on the surface at which material transfer was identified
 208 (see Figure 3) shows significantly lower adhesion than pristine sapphire measured outside the wear
 209 scar, indicating a distinct surface composition within the transfer film. On the chromium-coated
 210 wafer (Figure 5b), the wear scar exhibits a higher adhesion signal compared to the surrounding

211 smooth surface. Note that we used the same tip for before and after comparison measurements.
212 The observed adhesion contrast between sapphire and chromium surfaces demonstrates comple-
213 mentary changes at both sides of the contact.

214 **4 Discussion**

215 **4.1 From Microcontacts to Debris Generation**

216 Our results demonstrate that the sapphire-on-chromium interface forms sufficiently strong micro-
217 contacts to initiate material transfer from the chromium film onto the sapphire surface during fret-
218 ting. We hypothesize that, as fretting proceeds, the sapphire-on-chromium microcontacts (Figure 2)
219 generate sufficient stress to induce adhesive wear of the chromium film, resulting in chromium de-
220bris formation. The observations of craters and debris particles on the chromium surface (Figure 4)
221 are consistent with this interpretation.

222 To evaluate whether the simulated microcontacts (Figure 2b) can generate chromium debris
223 through adhesive wear, we apply the critical length scale model developed by Aghababaei and
224 Molinari [31]. This model defines a threshold lateral dimension d^* of contact patches, above which
225 crack propagation becomes energetically favorable, initiating debris formation via brittle frac-
226 ture [56]. The critical size is given by

$$227 \quad d^* = \lambda \cdot \frac{\Delta w}{\sigma_j^2 / G}$$

228 where Δw is the surface energy of the material to be fractured, σ_j is the shear strength of the con-
229 tact patch, G is the shear modulus of the softer material, and λ is a dimensionless geometric con-
230 stant. For chromium [5], we adopt $\Delta w = 2.25 \pm 0.15 \text{ J/m}^2$ and $G = 110 \pm 10 \text{ GPa}$ [57,58]. We
231 estimate the contact patch shear strength as $\sigma_j = \mu p$, where $\mu \approx 0.5$ is a representative friction
232 coefficient for sapphire–chromium interfaces under fretting conditions [47,48], and $\sim 1 \text{ GPa}$ is the
233 characteristic normal stress acting within load-bearing microcontacts (Figure 2d,e).

234 Since both the craters and detached debris in Figure 4 are laterally extended in the contact plane

235 but very shallow (tens of nanometers in depth/height), we treat the wear mechanism as plate-like
 236 rather than spherical. Following Aghababaei and Molinari [31], we therefore take the geometric
 237 factor λ in the range from 1 to $8/\pi$, where $8/\pi \approx 2.55$ corresponds to an idealized 2D circular
 238 particle. Using $\sigma_j = 500$ MPa, $\Delta w = 2.10\text{--}2.40$ J/m², and $G = 100\text{--}120$ GPa, we conclude that d^*
 239 should be in the range of 800 nm to 5 μm .
 240 This analysis indicates that brittle debris formation becomes feasible once sapphire–chromium con-
 241 tacts grow or coalesce into micrometer-scale contact patches. Based on the contact calculations in
 242 Figure 2d, the load-bearing contact patches span sub-micrometer to micrometer lateral dimensions,
 243 with clustered contact patches frequently exceeding 1 μm and reaching several micrometers. Im-
 244 portantly, experimental evidence supports the existence of such large contact patches: Figure 4b
 245 shows micrometer-scale wear-induced features distributed within the nominal Hertzian contact re-
 246 gion (radius ~ 10 μm). Moreover, the insets in Figure 4b and the corresponding height profiles in
 247 Figure 4c reveal crater-like features that reach lateral dimensions of up to ~ 1 μm .

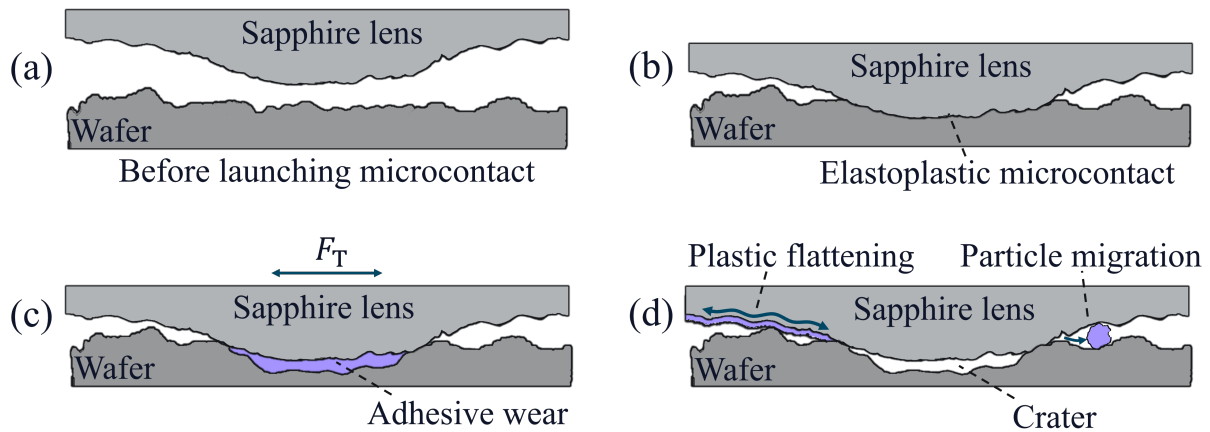


Figure 6: Illustration of (a,b) microcontact formation, (c) fretting-induced adhesive wear, and (d) subsequent plastic compaction and migration of the debris material. The typical size of craters and debris particles is a micrometer in plane and 10 nm in height/depth (see Figure 4).

248 Overall, Figure 4b and 4c place most fretting-generated craters and detached features directly
 249 within the predicted critical regime for brittle fracture. Together, these observations suggest that
 250 fretting-induced adhesive wear in our system proceeds via the nucleation of micrometer-scale frac-

251 tured debris, as schematically illustrated in Figure 6c, and motivate a closer examination of the re-
252 sulting crater morphology and transfer layers discussed below.

253 **4.2 How Debris Accumulates: Craters and Transfer Layers**

254 Craters in Figure 4b are elongated and aligned with the fretting direction within the Hertzian con-
255 tact zone, indicating that damage accumulation is governed by the imposed cyclic shear rather than
256 purely normal loading. This directional morphology supports the adhesive wear scenario depicted
257 in Figure 6c, where repeated tangential loading promotes growth in contact patches and subsequent
258 detachment events. Following detachment, the cratered regions remain exposed to continued fret-
259 ting, which may enable further fragmentation and redistribution of chromium fragments within the
260 contact.

261 The chromium debris generated during fretting is likely plastically compacted under repeated load-
262 ing, forming conformal contact with the sapphire surface and thereby contributing to the formation
263 of the thin (~ 5 nm) transfer film observed experimentally. Such transfer-film formation, in which
264 detached material spreads and compacts within the contact, is reminiscent of recent mechanistic
265 descriptions of metallic wear governed by transfer layer formation and interfacial cracking [33].

266 **4.3 The Peripheral Ring: A Geometric Escape Zone**

267 AFM measurements of the sapphire apex reveal two distinct topographic features after fretting: a
268 conformal transfer film within the Hertzian contact and a peripheral debris ring located just outside
269 the contact (Figure 3). The transfer film likely forms through plastic compaction of fine chromium
270 debris trapped within the contact (Figure 6d). In contrast, the formation of the peripheral ring re-
271 quires debris particles to migrate radially outward beyond the Hertzian contact area.

272 For a particle to escape the contact, it must reach a radial position Δr where the vertical gap be-
273 tween the sapphire lens and the wafer Δz equals or exceeds the particle height, as illustrated
274 schematically in Figure 7a,b. Assuming a representative debris particle height of $z \approx 25$ nm (Fig-
275 ure 4c) and a sapphire lens radius of $R = 1.59$ mm, we estimate that the gap equals the particle

276 height at a radial distance $r_{\text{ring}} > 13.5 \mu\text{m}$ from the contact center, so $\Delta r > 3 \mu\text{m}$ from the Hertzian
 277 contact edge (see Supporting Information for details).

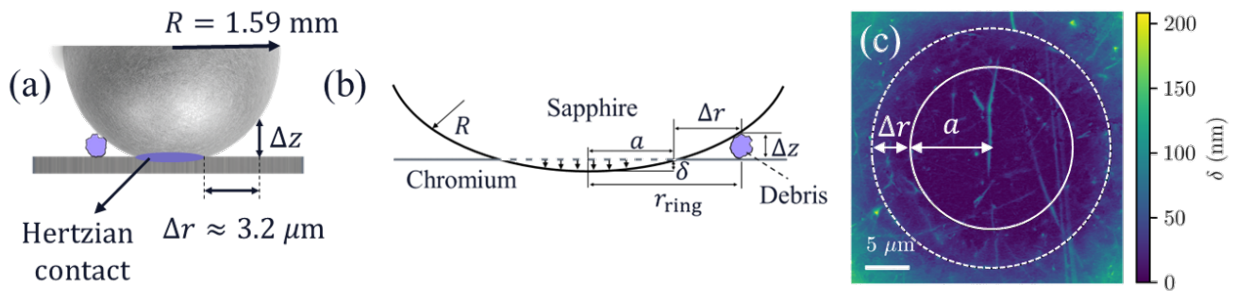


Figure 7: Formation of the peripheral debris ring during sapphire–chromium contact. (a) Schematic illustration of the Hertzian contact between a sapphire lens with radius $R = 1.59 \text{ mm}$ and a chromium-coated wafer. (b) Cross-sectional representation of the contact geometry showing the radial position r_{ring} where the gap between the sapphire surface and the chromium film Δz should be at least equal to the debris particle height. The Hertzian contact radius is a , and the elastic indentation depth is δ . A peripheral debris ring forms at a radial offset Δr from the contact edge. (c) Interfacial gap map obtained from elasto-plastic contact simulations based on the Tamaas library [51,52].

278 This estimate agrees well with the experimentally observed debris ring position shown in Figure 3.
 279 It also coincides with the predicted peripheral ring (dashed circle) in the simulated interfacial gap
 280 map in Figure 7c. Together, these results support a curvature-limited redistribution mechanism in
 281 which debris particles escape the contact and accumulate at radial positions where the geometry
 282 provides sufficient vertical clearance.

283 5 Conclusion

284 We present sapphire-on-chromium fretting experiments combined with detailed atomic force mi-
 285 croscopy analysis of the resulting wear scars. Using a topography difference method, we identify
 286 the formation of a conformal chromium-based transfer film of approximately 5 nm thickness on the
 287 sapphire surface after fretting. Adhesion measurements reveal a clear contrast between the transfer
 288 film and surrounding pristine sapphire regions, confirming the presence of a mechanically distinct
 289 interfacial layer.

290 We propose that the conformal transfer film forms through a two-step mechanism: (i) chromium
291 fragments detach from the coating by fracture during adhesive wear at micrometer-scale contact
292 patches, and (ii) the resulting debris particles are plastically compacted under continued cyclic
293 shear and adhere to the sapphire surface, forming a thin conformal layer within the Hertzian con-
294 tact region.

295 Debris generated near the edge of the contact is sheared radially outward. These larger particles ac-
296 cumulate in a ring-shaped region where the local interfacial gap, set by the lens curvature, becomes
297 comparable to the particle height and can accommodate their presence in the form of a peripheral
298 ring just outside the contact area.

299 Together, these results show that nanoscale transfer in partial-slip fretting proceeds through de-
300 bris formation, in-contact compaction into a conformal film, and curvature-controlled expulsion of
301 excess material. Understanding this sequence is essential for predicting and controlling material
302 redistribution in precision positioning interfaces.

303 **Supporting Information**

304 Supporting Information File 1:

305 File Name: SI_Formation_and_Compaction_of_Sub-10_nm_Transfer_Films.pdf

306 File Format: PDF

307 Title: Supporting Information

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